

**Problem Set 8**  
 Applied Statistics and Econometrics II  
 Spring 2018, NYU  
 Ercan Karadas

(Sent by 3pm, April 25)

[1] Consider the following data generating process

$$\begin{aligned} x_t + \beta y_t &= u_{1t}, & \text{where } u_{1t} &= \theta u_{1,t-1} + \epsilon_{1t} \\ x_t + \alpha y_t &= u_{2t}, & \text{where } u_{2t} &= \rho u_{2,t-1} + \epsilon_{2t} \end{aligned}$$

where  $|\rho| < 1$  and

$$\begin{pmatrix} \epsilon_{1t} \\ \epsilon_{2t} \end{pmatrix} \sim D \left[ \begin{pmatrix} 0 \\ 0 \end{pmatrix}, \begin{pmatrix} \sigma_1^2 & \gamma \\ \gamma & \sigma_1^2 \end{pmatrix} \right]$$

where  $D$  denotes a generic distribution.

- a) Derive the degree of integratedness of the two series,  $x_t$  and  $y_t$ , explicitly stating the parameter restrictions required in each case.
- b) Under what coefficient restrictions are  $x$  and  $y$  cointegrated? What are the cointegrating vectors in these cases?
- c) Choose a particular set of coefficients that ensures  $x$  and  $y$  are cointegrated and derive the following representations:
  - i. the moving-average: that is  $(x_t \ y_t)'$  on the left hand side,  $(\epsilon_{1t} \ \epsilon_{2t})'$  and its lags on the right hand side.
  - ii. The autoregressive in the levels: that is,  $(x_t \ y_t)'$  on the right hand side, and lags of  $(x_t \ y_t)'$  and  $(\epsilon_{1t} \ \epsilon_{2t})'$  on the right hand side.
  - iii. The Error-Correction Representation: that is,  $(\Delta x_t \ \Delta y_t)'$  as a function of  $z_{t-1}$  and residuals (no need to be specific about the residuals).
- d) In general, discuss the pros and cons of obtaining impulse responses from a VAR estimated in the levels, as in part (c)-(i) and one in VEC form, as in part (c)-(iii).

[2] Consider the following data generating process

$$\begin{aligned} x_t + y_t &= v_t, & v_t(1 - \rho_1 L) &= \epsilon_{1t} \\ 2x_t + y_t &= u_t, & u_t(1 - \rho_2 L) &= \epsilon_{2t} \end{aligned}$$

where  $|\rho| < 1$  and

$$\begin{pmatrix} \epsilon_{1t} \\ \epsilon_{2t} \end{pmatrix} \sim N \left[ \begin{pmatrix} 0 \\ 0 \end{pmatrix}, \begin{pmatrix} \sigma_1^2 & 0 \\ 0 & \sigma_1^2 \end{pmatrix} \right]$$

where  $D$  denotes a generic distribution.

- a) Determine whether this system is stationary, non-stationary, or non-stationary but cointegrated according to the following scenarios:
- i.  $|\rho_1| < 1, |\rho_2| < 1$
  - ii.  $|\rho_1| = 1, |\rho_2| < 1$
  - iii.  $|\rho_1| = 1, |\rho_2| = 1$
- b) Obtain the reduced-form, autoregressive representation of the system in the levels when it is cointegrated.
- c) Given the representation that you have just found, calculate the reduced-form, impulse response function coefficient matrices,  $\Psi_s$  for periods  $s = 0, 1$ , and 2 for  $\rho_2 = 0.5$ . What is  $\Psi_s$  as  $s \rightarrow \infty$ ? Given the reduced form impulse response matrices, calculate the structural impulse responses for periods 0, 1, 2. What is happening as  $s \rightarrow \infty$ ? Explain this result.
- d) Find the moving-average representation of the system and the cointegrating vector when it is cointegrated.
- e) Describe how you could estimate the cointegrating vector in a regression of  $y_t$  on  $x_t$  which is well behaved in small samples.

[3] Consider the following bivariate VAR

$$\begin{aligned}y_{1t} &= 0.3y_{1t-1} + 0.8y_{2t-1} + \epsilon_{1t} \\y_{2t} &= 0.9y_{1t-1} + 0.4y_{2t-1} + \epsilon_{2t}\end{aligned}$$

where  $E(\epsilon_{1t}\epsilon_{1\tau}) = 1$  for  $t = \tau$  and 0 otherwise;  $E(\epsilon_{2t}\epsilon_{2\tau}) = 2$  for  $t = \tau$  and 0 otherwise; and  $E(\epsilon_{1t}\epsilon_{2\tau}) = 0$  for all  $t, \tau$ .

Answer the following questions.

- a) Is this system covariance-stationary?
- b) Calculate  $\Psi_s = \frac{\partial y_{t+s}}{\partial \epsilon_t}$  for  $s = 0, 1, 2$ . What is the limiting expression as  $s \rightarrow \infty$ .
- c) Calculate the fraction of the MSE of the two period-ahead forecast error for variable 1,  $E[y_{1,t+2} - \hat{E}(y_{1,t+2}|y_t, y_{t-1}, \dots)]^2$ , that is due to  $\epsilon_{1,t+1}$  and  $\epsilon_{1,t+2}$ .

[4] Consider the following VAR

$$\begin{aligned}y_t &= (1 + \beta)y_{t-1} - \beta\alpha x_{t-1} + \epsilon_{1t} \\x_t &= \gamma y_{t-1} + (1 - \gamma\alpha)x_{t-1} + \epsilon_{2t}\end{aligned}$$

Answer the following questions.

- a) Show that this VAR is not-stationary.

- b) Find the cointegrating vector and derive the VECM representation.
- c) Transform the model so that it involves the error correction term (call it  $z$ ) and a difference stationary variable (call it  $\Delta w_t$ ).  $w$  will be a linear combination of  $x$  and  $y$  but should not contain  $z$ . *Hint:* the weights in this linear combination will be related the coefficients of the error correction terms.
- d) Verify that  $y$  and  $x$  can be expressed as a linear combination of  $w$  and  $z$ . Give an interpretation as a decomposition of the vector  $(yx)'$  into permanent and transitory components.

[5] Consider the following VECM

$$\Delta y_t = c + \alpha \beta' y_{t-1} + \epsilon_t, \quad \epsilon_{it} \sim iid(0, \sigma^2)$$

where  $\alpha = (\alpha_1, 0)'$  and  $\beta = (1, -\beta_2)'$ . Equation by equation, the system is given by

$$\begin{aligned} \Delta y_{1t} &= c_1 + \alpha_1(y_{1,t-1} - \beta_2 y_{2,t-1}) + \epsilon_{1t} \\ \Delta y_{2t} &= c_2 + \epsilon_{2t} \end{aligned}$$

Answer the following questions.

- a) From the VECM representation above, derive the VECM representation

$$\Delta y_t = c + \Pi y_{t-1} + \epsilon_t$$

and VAR representation

$$y_t = c + A y_{t-1} + \epsilon_t$$

- b) Based on the given values of the elements in  $\alpha$  and  $\beta$ , determine  $\alpha_\perp$  and  $\beta_\perp$  such that  $\alpha' \alpha_\perp = 0$  and  $\beta' \beta_\perp = 0$ .
- c) Using the Granger representation theorem determine that  $\Psi(1) = \beta_\perp (\alpha'_\perp I_2 \beta'_\perp)^{-1} \alpha_\perp$ , where  $\Psi(L)$  is the moving average polynomial corresponding to the VECM system above and  $I_2$  is the identity matrix of order 2. *Hint:* you may show this result by showing that  $\Psi(1)$  is orthogonal to the cointegrating space.
- d) Using the Beveridge-Nelson decomposition and the result in (c), determine the common trend in the VECM system.
- e) Show that  $\beta' y_t$  follows an AR(1) process and show that this AR(1) is stable provided that  $-2 < \alpha_1 < 0$ . What can you say about the system when  $\alpha_1 = 0$ ?

[6] Consider the following process,

$$y_t \sim \ln(\beta y_{t-1}) + \epsilon_t, \quad y_0 = 1, \quad \epsilon_t \sim iidD(0, 1), \quad \beta > 0$$

- a) Discuss how you would determine whether this process is stationary (although it is not necessary to derive this analytically, it is a bonus if you can determine for what values of  $\beta$  will the process be stationary).

- b) Assuming the regularity conditions for QMLE are met, find the conditional QMLE estimator for  $\beta$  (i.e., conditional on  $y_0 = 1$ ). Assume the variance of the  $\epsilon$  is known to be 1.
- c) Assuming the regularity conditions for QMLE are met, derive the asymptotic distribution for  $\hat{\beta}$ . Note, you do not need to derive this from first principles, you may use QMLE results.
- d) Given the distribution of  $\hat{\beta}$ , find the distribution of  $\ln \hat{\beta}$ .
- e) Instead, given  $\hat{\beta}$  from QMLE, describe in steps how you would construct a 95% confidence interval for  $\ln \beta$  with bootstrap.
- f) Suppose Instead that you asked to construct a 95% confidence interval with the bootstrap for  $\ln \beta$  from the least squares regression,

$$y_t - \ln y_{t-1} = \ln \beta + \epsilon_t$$

with  $\sigma_\epsilon = 1$  and known. Is the percentile method pivotal? Does the bootstrap provide an asymptotic refinement in this case?

- g) For an initial guess for  $\beta$ , say  $\beta_1$ , construct the first step in the BHHH algorithm.

[7] Consider a log-linearized present value model,

$$d_t - p_t = \rho^{-1} E_t \sum_{j=1}^{\infty} \rho^j (r_{t+j} - \Delta d_{t+j}),$$

where  $\Delta d_{t+j}$  dividend growth,  $d_t - p_t$  is the log of the dividend-price ratio, and  $r_t$  is the log of the gross return. Using a log-linear approximation,  $r_t$  can be approximated as

$$r - t = \Delta d_t - \rho(d_t - p_t) + (d_{t-1} - p_{t-1}).$$

The parameter  $0 < \rho < 1$  is a discount factor, which we assume is known, and constants are suppressed for convenience.

- a) Suppose  $d_t$  has a unit root. For studying this relationship, what would be a sensible specification for a vector time-series model? Explain your modeling choice.
- b) Suppose you wanted to test the hypothesis that expected returns are constant. This imposes a collection of nonlinear cross-equation restrictions on your vector time-series model that we can represent as  $R(\theta) = 0$ . Describe how you would test those restrictions.
- c) What is the asymptotic distribution of your test statistic? Explain.